

5. MAGNETOSTATICS



Electric vs Magnetic Comparison

Attributes of electrostatics and magnetostatics.

Attribute	Electrostatics	
Sources	Stationary charges ρ_v	
Fields and Fluxes	E and D	$\mathbf{J} = \sigma \mathbf{E}$
Constitutive parameter(s)	ϵ and σ	
Governing equations		
• Differential form	$\nabla \cdot \mathbf{D} = \rho_v$ $\nabla \times \mathbf{E} = 0$	
• Integral form	$\oint_S \mathbf{D} \cdot d\mathbf{s} = Q$ $\oint_C \mathbf{E} \cdot d\mathbf{l} = 0$	
Potential	Scalar V , with $\mathbf{E} = -\nabla V$	
Energy density	$w_e = \frac{1}{2} \epsilon E^2$	
Force on charge q	$\mathbf{F}_e = q\mathbf{E}$	
Circuit element(s)	C and R	

Most dielectrics $\mu = \mu_0$ excluding ferromagnetic materials

Gauss's Law

E field is conservative

Gauss's law (integral)

Conservative E field

Electric potential and E

Electrostatic energy density (J/m^3)

Electric Force due to charge (N) – parallel E

$CV = Q$
 $RC = \epsilon/\sigma$

Geometry

Electric vs Magnetic Comparison

Attributes of electrostatics and magnetostatics.

Attribute	Electrostatics	Magnetostatics
Sources	Stationary charges ρ_v	Steady currents \mathbf{J}
Fields and Fluxes	\mathbf{E} and \mathbf{D}	\mathbf{H} and \mathbf{B}
Constitutive parameter(s)	ϵ and σ	μ
Governing equations		
• Differential form	$\nabla \cdot \mathbf{D} = \rho_v$ $\nabla \times \mathbf{E} = 0$	$\nabla \cdot \mathbf{B} = 0$ $\nabla \times \mathbf{H} = \mathbf{J}$
• Integral form	$\oint_S \mathbf{D} \cdot d\mathbf{s} = Q$ $\oint_C \mathbf{E} \cdot d\mathbf{l} = 0$	$\oint_S \mathbf{B} \cdot d\mathbf{s} = 0$ $\oint_C \mathbf{H} \cdot d\mathbf{l} = I$
Potential	Scalar V , with $\mathbf{E} = -\nabla V$	Vector \mathbf{A} , with $\mathbf{B} = \nabla \times \mathbf{A}$
Energy density	$w_e = \frac{1}{2}\epsilon E^2$	$w_m = \frac{1}{2}\mu H^2$
Force on charge q	$\mathbf{F}_e = q\mathbf{E}$	$\mathbf{F}_m = q\mathbf{u} \times \mathbf{B}$
Circuit element(s)	C and R	L

Parallel Properties

Electric & Magnetic Forces

Magnetic force

$$\mathbf{F}_m = q\mathbf{u} \times \mathbf{B} \quad (\text{N})$$

B (Tesla)

U indicates the velocity of the moving charge

F_m is the force acting on the moving charge

F_m is perpendicular with U and B

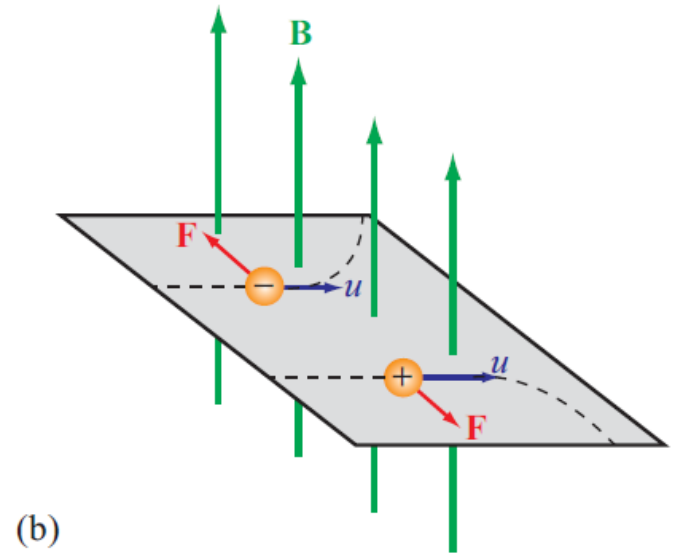
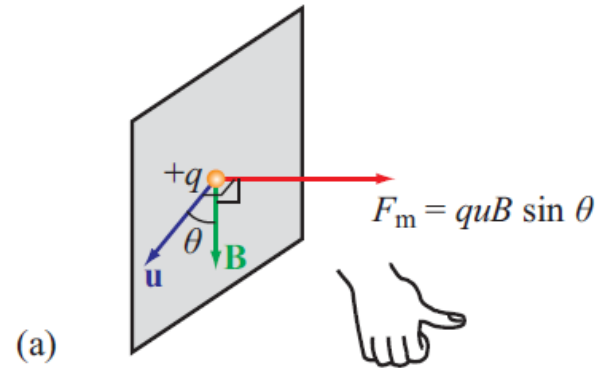
Note: $F_m = quB\sin(\theta) \rightarrow$ Max when angle is 90!

Electromagnetic (Lorentz) force

$$\mathbf{F} = \mathbf{F}_e + \mathbf{F}_m = q\mathbf{E} + q\mathbf{u} \times \mathbf{B} = q(\mathbf{E} + \mathbf{u} \times \mathbf{B}).$$

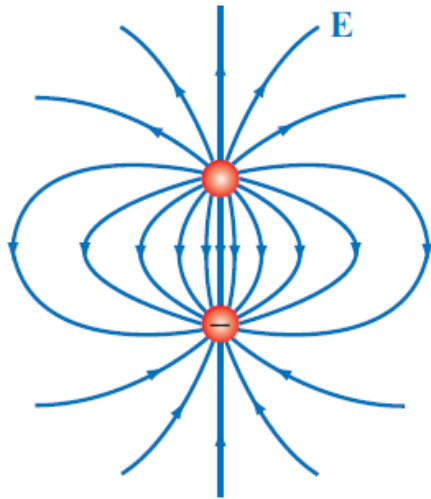
Important Note:

$$(q) \mathbf{dl} = \mathbf{u} dt (q) \rightarrow q/dt (\mathbf{dl}) = I \mathbf{dl} = \mathbf{u} q$$

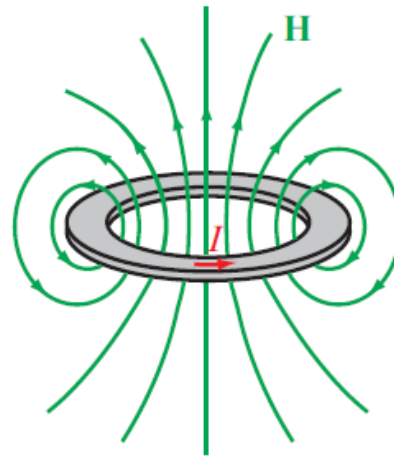


The direction of F_m can change depending on the charge!

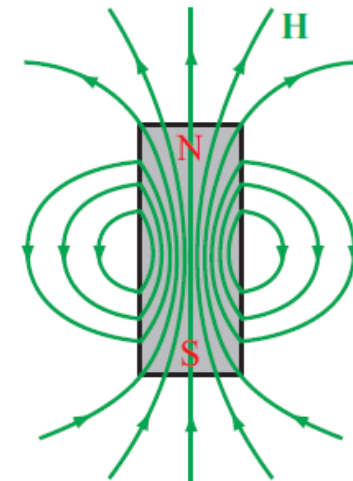
Magnetic Dipole



(a) Electric dipole



(b) Magnetic dipole



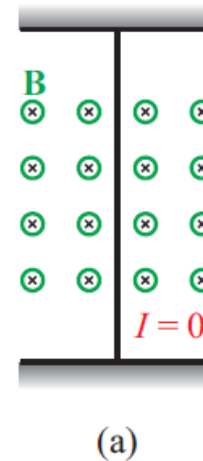
(c) Bar magnet

Because a circular loop exhibits a magnetic field pattern similar to the electric field of an electric dipole, it is called a *magnetic dipole*

Magnetic Force on a Current Element

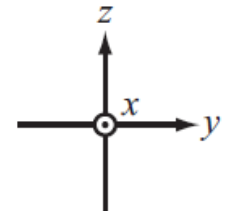
Differential force dF_m on a differential current $I dl$:

$$d\mathbf{F}_m = I d\mathbf{l} \times \mathbf{B} \quad (\text{N}).$$



I Moving $+z!$
 $F_m?$

I moving $-z!$
 $F_m?$



Important Note:

$$(q) d\mathbf{l} = \mathbf{u} dt (q) \rightarrow q/dt (d\mathbf{l}) = I d\mathbf{l} = \mathbf{u} q$$

Magnetic Force on a Current Element

Differential force $d\mathbf{F}_m$ on a differential current $I d\mathbf{l}$:

$$d\mathbf{F}_m = I d\mathbf{l} \times \mathbf{B} \quad (\text{N}).$$

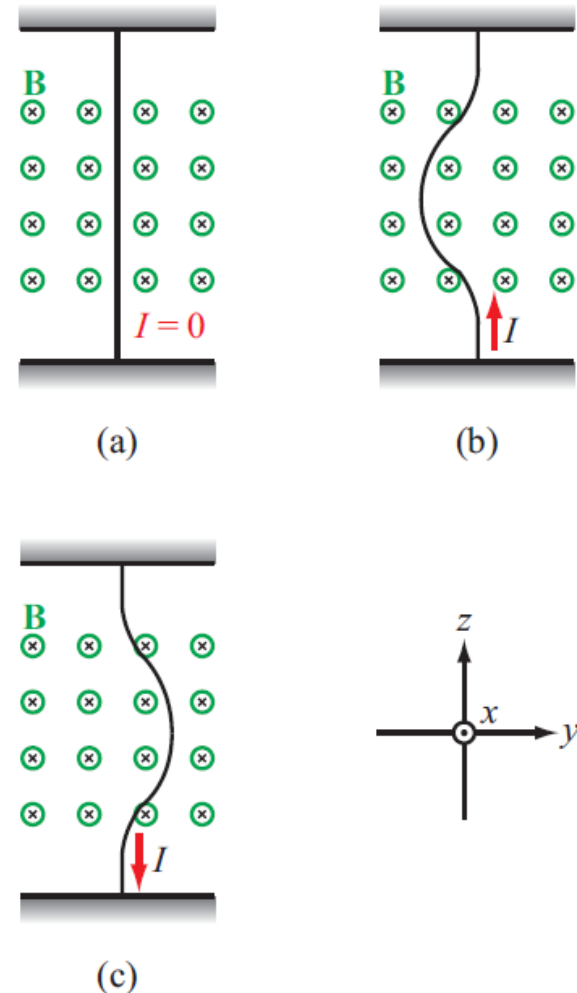
For a closed circuit of contour C carrying a current I , the total magnetic force is

$$\mathbf{F}_m = I \oint_C d\mathbf{l} \times \mathbf{B} \quad (\text{N}).$$

If a **closed wire loop** resides in External \mathbf{B}

Vector sum
of infinitesimal
vectors $d\mathbf{l}$
Over closed contour C

$$\mathbf{F}_m = I \left(\oint_C d\mathbf{l} \right) \times \mathbf{B} = 0.$$



Important Note:

$$(q) \mathbf{dl} = \mathbf{u} dt (q) \rightarrow q/dt (\mathbf{dl}) = I \mathbf{dl} = \mathbf{u} q$$

Biot-Savart Law

Magnetic field induced by a differential current:

$$d\mathbf{H} = \frac{I}{4\pi} \frac{d\mathbf{l} \times \hat{\mathbf{R}}}{R^2} \quad (\text{A/m})$$

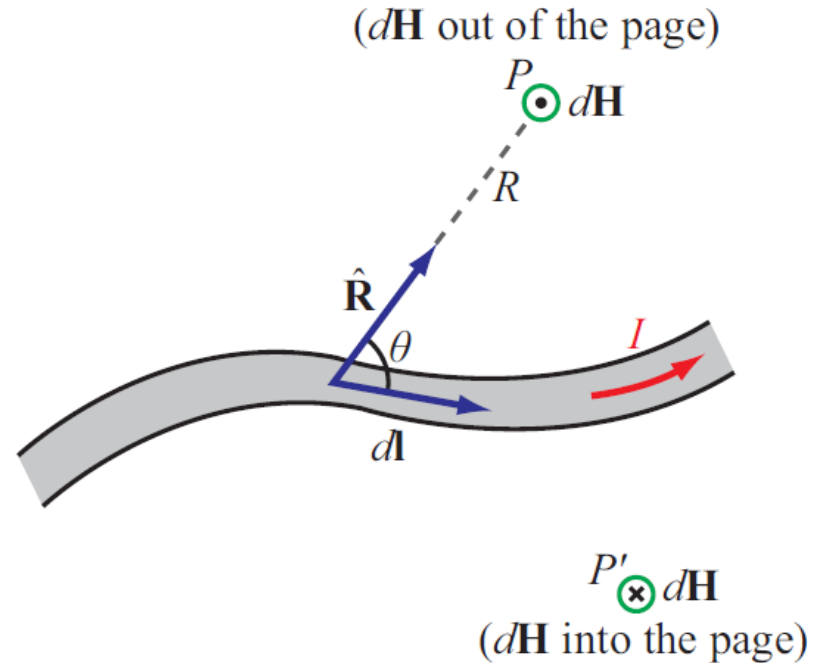
Hans Oersted demonstrated that steady current induces \mathbf{H}
Thus, differential \mathbf{H} proportional to steady current flowing through differential vector length

R is the distance vector between $d\mathbf{l}$ and the observation point!

For the entire length:

$$\mathbf{H} = \frac{I}{4\pi} \int_l \frac{d\mathbf{l} \times \hat{\mathbf{R}}}{R^2} \quad (\text{A/m}),$$

where l is the line path along which I exists.



$$\hat{\mathbf{R}} = \mathbf{R} / |\mathbf{R}|$$

Magnetic Field due to Current Densities

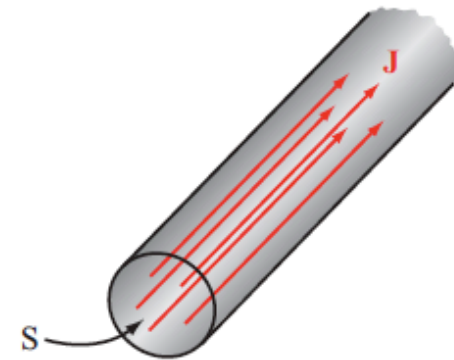
$$\mathbf{H} = \frac{I}{4\pi} \int_l \frac{d\mathbf{l} \times \hat{\mathbf{R}}}{R^2} \quad (\text{A/m}),$$

where l is the line path along which I exists.

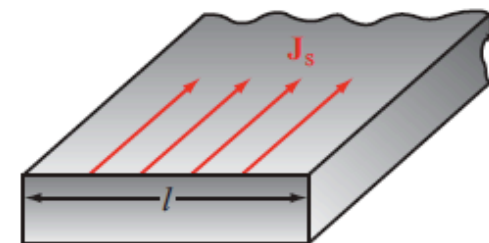
one \rightarrow

$$\mathbf{H} = \frac{1}{4\pi} \int_s \frac{\mathbf{J}_s \times \hat{\mathbf{R}}}{R^2} ds \quad (\text{surface current}),$$

$$\mathbf{H} = \frac{1}{4\pi} \int_v \frac{\mathbf{J} \times \hat{\mathbf{R}}}{R^2} dV \quad (\text{volume current}).$$



(a) Volume current density \mathbf{J} in A/m^2



(b) Surface current density \mathbf{J}_s in A/m

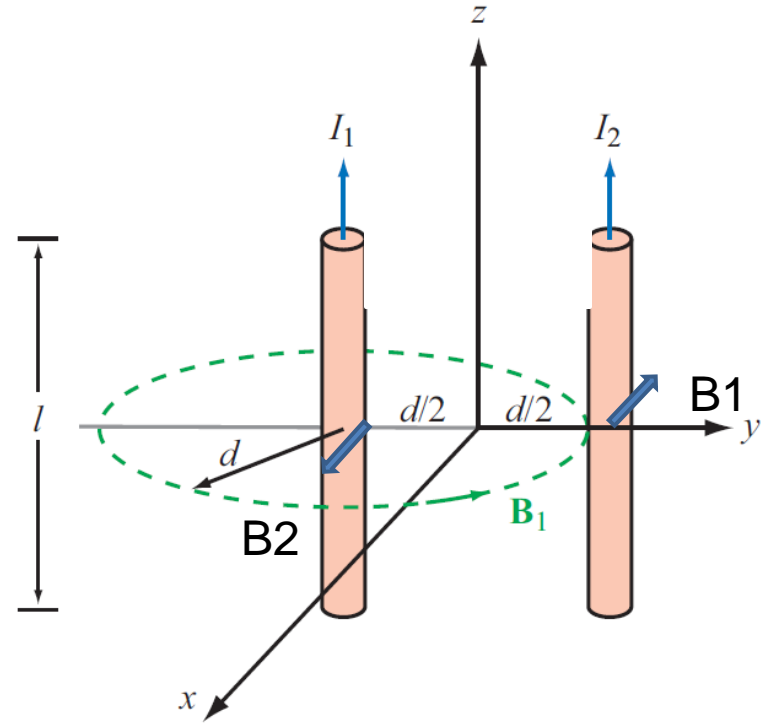
Forces on Parallel Conductors

$$d\mathbf{F}_m = I d\mathbf{l} \times \mathbf{B} \quad (\text{N}).$$

External B

Which direction is F_1 ?

What about F_2 ?



Forces on Parallel Conductors

$$\mathbf{B}_1 = -\hat{\mathbf{x}} \frac{\mu_0 I_1}{2\pi d} .$$

$$\begin{aligned} \mathbf{F}_2 &= I_2 l \hat{\mathbf{z}} \times \mathbf{B}_1 = I_2 l \hat{\mathbf{z}} \times (-\hat{\mathbf{x}}) \frac{\mu_0 I_1}{2\pi d} \\ &= -\hat{\mathbf{y}} \frac{\mu_0 I_1 I_2 l}{2\pi d} , \end{aligned}$$

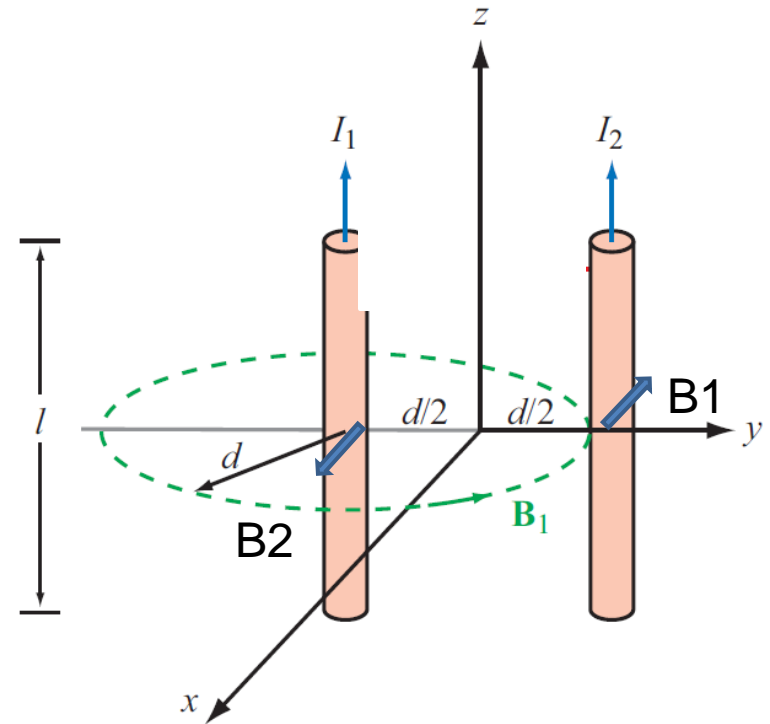
and the corresponding force per unit length is

$$\mathbf{F}'_2 = \frac{\mathbf{F}_2}{l} = -\hat{\mathbf{y}} \frac{\mu_0 I_1 I_2}{2\pi d} .$$

A similar analysis performed for the force per unit length exerted on the wire carrying I_1 leads to

$$\mathbf{F}'_1 = \hat{\mathbf{y}} \frac{\mu_0 I_1 I_2}{2\pi d} .$$

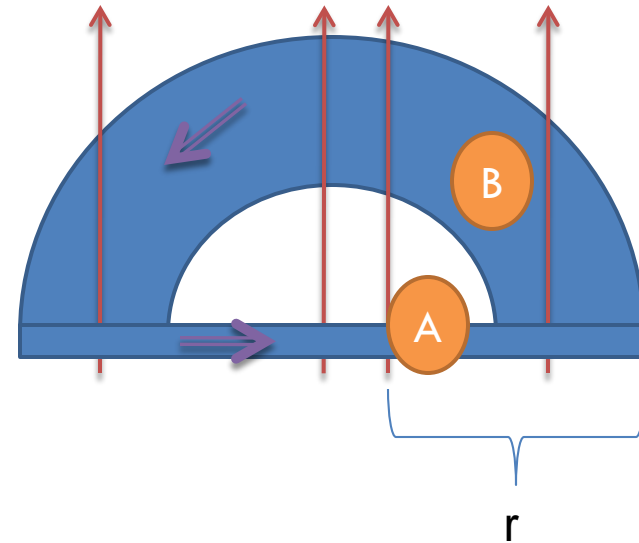
Parallel wires attract if their currents are in the same direction, and repel if currents are in opposite directions.



Notes
A1

Example

- What is B vector?
- Find F at pt A and B



Notes
A2

Find the Differential Magnetic Field Along an Infinitely Long Conductor Carrying I

$$d\mathbf{H} = \frac{I}{4\pi} \frac{d\mathbf{l} \times \hat{\mathbf{R}}}{R^2} \quad (\text{A/m})$$

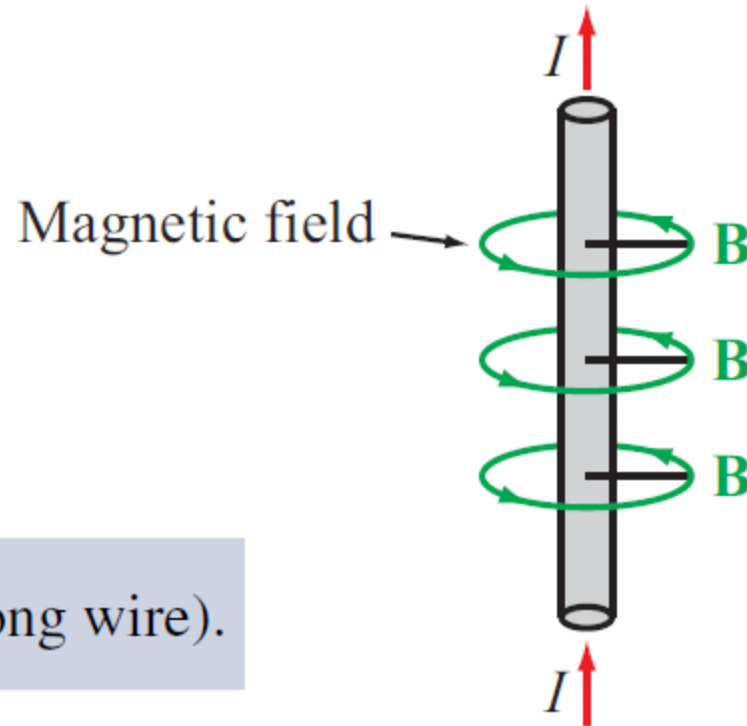
we find dH in x,y,z

What is the direction of dH?

Magnetic Field of Long Conductor

$$d\mathbf{H} = \frac{I}{4\pi} \frac{d\mathbf{l} \times \hat{\mathbf{R}}}{R^2} \quad (\text{A/m})$$

$$\mathbf{B} = \hat{\phi} \frac{\mu_0 I}{2\pi r} \quad (\text{infinitely long wire}).$$



Maxwell's Equations

Maxwell's Equations for Electrostatics

Name	Differential Form	Integral Form
Gauss's law	$\nabla \cdot \mathbf{D} = \rho_v$	$\oint_S \mathbf{D} \cdot d\mathbf{s} = Q$
Kirchhoff's law	$\nabla \times \mathbf{E} = 0$	$\oint_C \mathbf{E} \cdot d\mathbf{l} = 0$

Magnostatic Filed Properties

- Gauss's Law
 - ▣ Electrostatic
- Ampere's Law
 - ▣ Electrostatic

Governing equations

• Differential form

$$\nabla \cdot \mathbf{D} = \rho_v$$

$$\nabla \times \mathbf{E} = 0$$

• Integral form

$$\oint_S \mathbf{D} \cdot d\mathbf{s} = Q$$

$$\oint_C \mathbf{E} \cdot d\mathbf{l} = 0$$

$$\nabla \cdot \mathbf{B} = 0$$

There is no single magnetic dipole

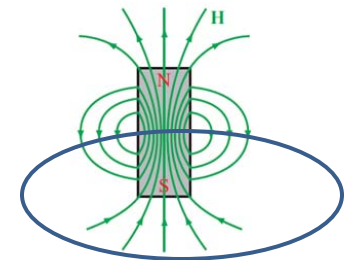
$$\nabla \times \mathbf{H} = \mathbf{J}$$

$$\oint_S \mathbf{B} \cdot d\mathbf{s} = 0$$

Gauss's Law for Magnetic

$$\oint_C \mathbf{H} \cdot d\mathbf{l} = I$$

Total Current Passing Through Surface S (open surface)



Net magnetic flux is zero

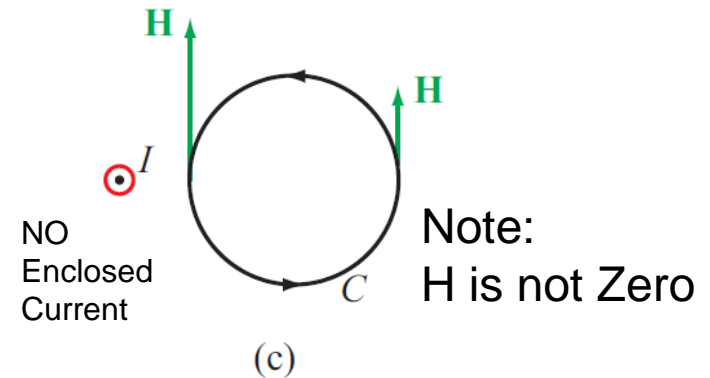
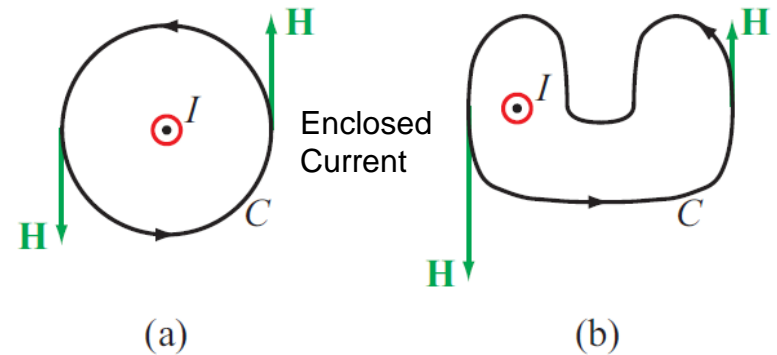
Ampère's Law

$$\nabla \times \mathbf{H} = \mathbf{J} \quad \longleftrightarrow \quad \oint_C \mathbf{H} \cdot d\boldsymbol{\ell} = I$$

$$I = \int_S \mathbf{J} \cdot d\mathbf{s} \quad (\text{A}).$$

Open Surface

Convection Current Density



the line integral of \mathbf{H} is zero for the contour in (c) because the current I (denoted by the symbol \odot) is not enclosed by the contour C .

Magnetic Properties of Materials

- Depends on how the magnetic dipole moments (\mathbf{m}) of atoms are changed due to external magnetic field
 - ▣ $\mathbf{m} = I A$ (current * area of the loop) with direction based on right-hand-rule
- Magnetization in materials is due to
 - ▣ Orbital motions \rightarrow orbital magnetic moment (m_o)
 - Most materials are nonmagnetic when there is no magnetic field \rightarrow atoms are randomly oriented \rightarrow very small net magnetic moment
 - ▣ Electron spin \rightarrow spin magnetic moment (m_s)
 - If odd number of e \rightarrow unpaired electrons \rightarrow net nonzero m_s
- Three types of materials
 - ▣ Diamagnetic \rightarrow (de / out of)
 - ▣ Paramagnetic \rightarrow (para is near)
 - ▣ Ferromagnetic \rightarrow (ferrum or iron)

Magnetic Permeability

M = Magnetization Vector = vector sum of magnetic dipole moments

$$\mathbf{B} = \mu_0 \mathbf{H} + \mu_0 \mathbf{M} = \mu_0 (\mathbf{H} + \mathbf{M})$$

Magnetic susceptibility

$$\mathbf{M} = \chi_m \mathbf{H}$$

$$\mathbf{B} = \mu_0 (\mathbf{H} + \chi_m \mathbf{H}) = \mu_0 (1 + \chi_m) \mathbf{H},$$

$$\mathbf{B} = \mu \mathbf{H},$$

Magnetic permeability

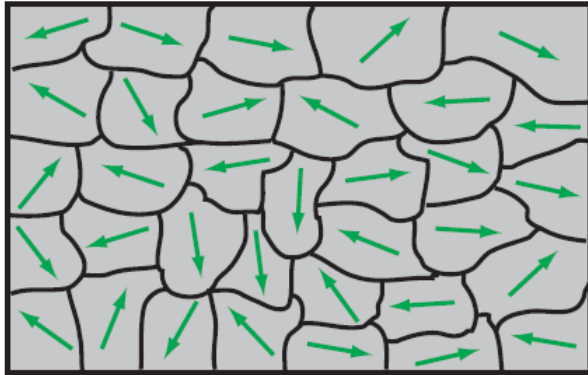
Properties of magnetic materials.

	Diamagnetism	Paramagnetism	Ferromagnetism
Permanent magnetic dipole moment	No	Yes, but weak	Yes, and strong
Primary magnetization mechanism	Electron orbital magnetic moment	Electron spin magnetic moment	Magnetized domains
Direction of induced magnetic field (relative to external field)	Opposite	Same	Hysteresis
Common substances	Bismuth, copper, diamond, gold, lead, mercury, silver, silicon	Aluminum, calcium, chromium, magnesium, niobium, platinum, tungsten	Iron, nickel, cobalt
Typical value of χ_m Typical value of μ_r	$\approx -10^{-5}$ ≈ 1	$\approx 10^{-5}$ ≈ 1	$ \chi_m \gg 1$ and hysteretic $ \mu_r \gg 1$ and hysteretic

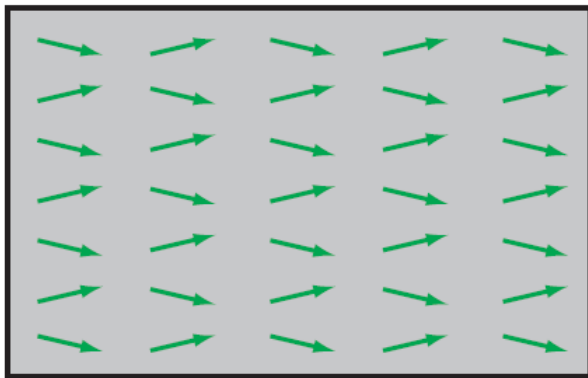
$$\mathbf{B} = \mu_0(\mathbf{H} + \chi_m \mathbf{H}) = \mu_0(1 + \chi_m)\mathbf{H},$$

$$\mathbf{B} = \mu \mathbf{H},$$

Magnetic Hysteresis



(a) Unmagnetized domains



(b) Magnetized domains

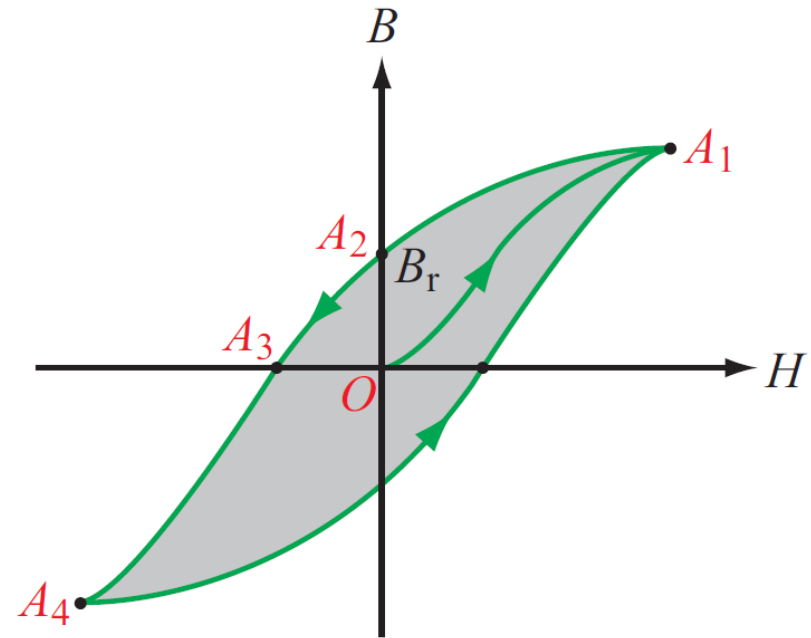
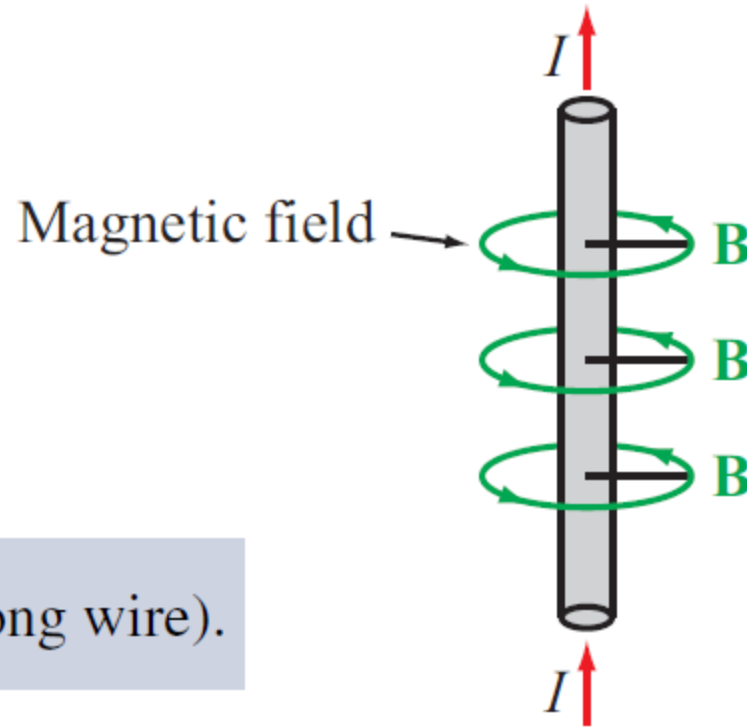


Figure 5-22: Typical hysteresis curve for a ferromagnetic material.

Magnetic Field of Long Conductor

$$d\mathbf{H} = \frac{I}{4\pi} \frac{d\mathbf{l} \times \hat{\mathbf{R}}}{R^2} \quad (\text{A/m})$$

$$\mathbf{B} = \hat{\phi} \frac{\mu_0 I}{2\pi r} \quad (\text{infinitely long wire}).$$

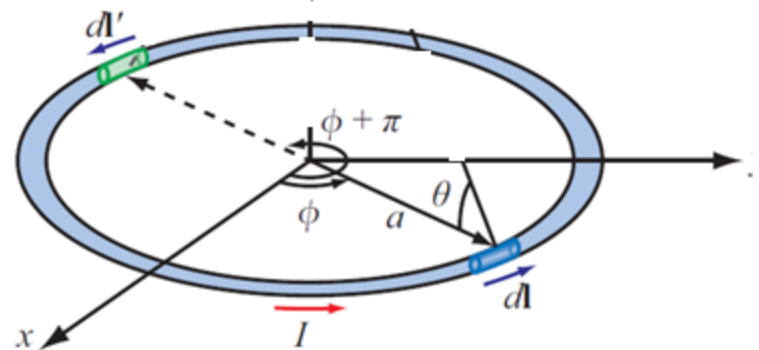


Notes
B0 – Prove!

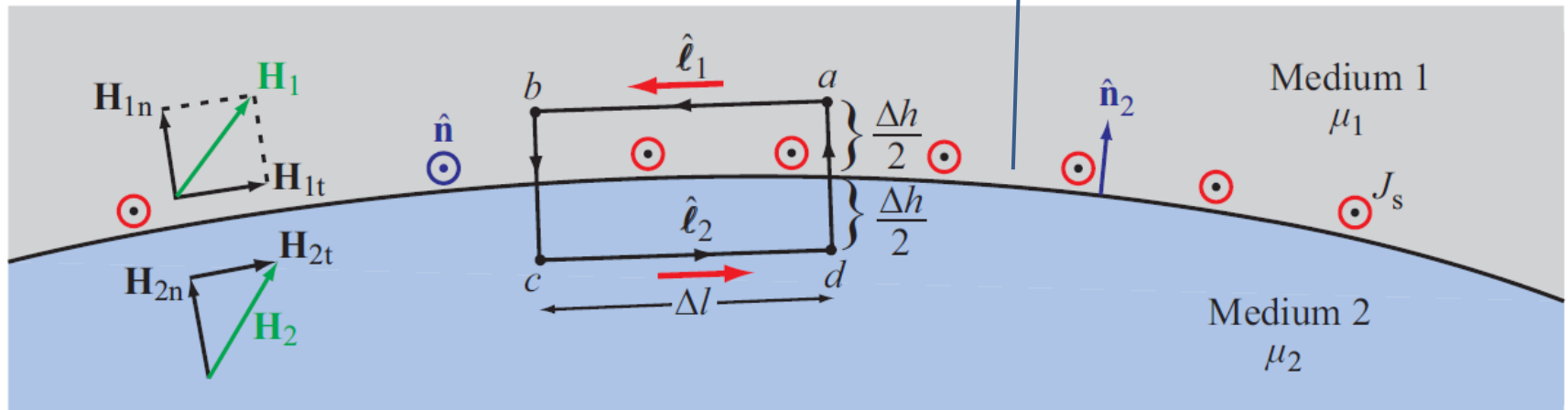
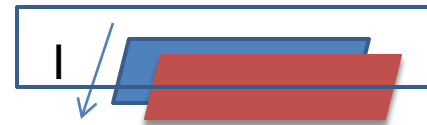
Assuming a loop carrying current – Find the magnetic field

- Do it on your own!
 - ▣ Compare it with the previous case!
 - ▣ What happens if you are in the middle of the loop?

$$\mathbf{H} = \hat{\mathbf{z}} \frac{Ia^2}{2(a^2 + z^2)^{3/2}} \quad (\text{A/m})$$



Boundary Conditions



Electrostatic

$$\oint_S \mathbf{D} \cdot d\mathbf{s} = Q \quad \rightarrow \quad D_{1n} - D_{2n} = \rho_s.$$

$$\hat{\mathbf{n}}_2 \times (\mathbf{H}_1 - \mathbf{H}_2) = \mathbf{J}_s.$$

By analogy, application of Gauss's law for magnetism, as expressed by Eq. (5.44), leads to the conclusion that

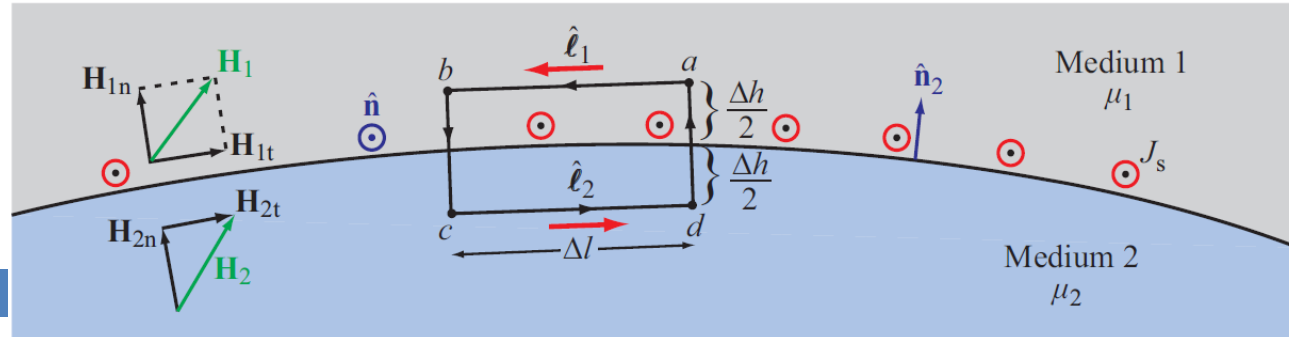
$$\oint_S \mathbf{B} \cdot d\mathbf{s} = 0 \quad \rightarrow \quad B_{1n} = B_{2n}.$$

Surface currents can exist only on the surfaces of perfect conductors and superconductors. Hence, *at the interface between media with finite conductivities*, $\mathbf{J}_s = 0$ and

$$H_{1t} = H_{2t}.$$

Thus the normal component of \mathbf{B} is continuous across the boundary between two adjacent media.

Example:



- Determine the angle between \mathbf{H}_1 and $\hat{\mathbf{n}}_2 = \hat{\mathbf{z}}$ if $\mathbf{H}_2 = (\hat{\mathbf{x}}3 + \hat{\mathbf{z}}2)$ (A/m), $\mu_1 = 2$, and $\mu_2 = 8$, and $J_s = 0$.

- ▣ Find H_{1t}
- ▣ Find H_{1n}

$$\begin{aligned}\mathbf{H}_2 &= \hat{\mathbf{x}}3 + \hat{\mathbf{z}}2 \\ H_{1x} &= H_{2x} = 3 \\ \mu_1 H_{1z} &= \mu_2 H_{2z} \\ H_{1z} &= \frac{\mu_2}{\mu_1} H_{2z} = \frac{8}{2} \times 2 = 8\end{aligned}$$

$$\begin{aligned}\mathbf{H}_1 &= \hat{\mathbf{x}}3 + \hat{\mathbf{z}}8 \\ \mathbf{H}_1 \cdot \hat{\mathbf{z}} &= H_1 \cos \theta\end{aligned}$$

$$\cos \theta = \frac{\mathbf{H}_1 \cdot \hat{\mathbf{z}}}{H_1} = \frac{8}{\sqrt{9+64}} = \frac{8}{\sqrt{73}} = 0.936$$

$$\theta = 20.6^\circ.$$

Notes
B1

Magnetic Flux

$$\nabla \times \mathbf{H} = \mathbf{J} \quad \longleftrightarrow \quad \oint_C \mathbf{H} \cdot d\boldsymbol{\ell} = I$$

Note:

Tesla = N / A.m = Wb /m²

μ_0 has unit of H/m

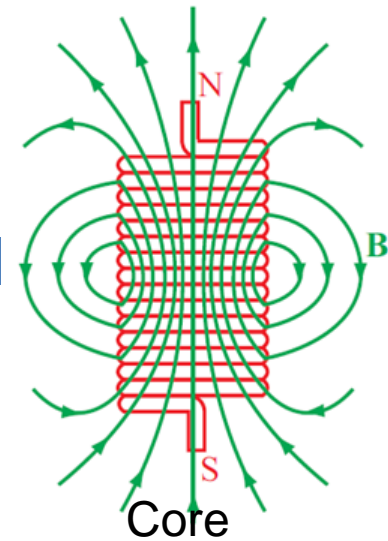
H = Wb /A

Magnetic Flux

$$\Phi = \int_S \mathbf{B} \cdot d\mathbf{s} \quad (\text{Wb}).$$

Can be positive or negative

Inductors



- Capacitors
 - ▣ Store Energy in E Field between plates
- Inductors
 - ▣ Generate uniform magnetic field when I is passing
 - ▣ Store Energy in H field along the current carrying conductor
- Inductance is related to magnetic flux and current
 - ▣ Self-inductance
 - ▣ Mutual inductance (e.g., B_{12} , L_{12})

Solenoid

Inside the solenoid:

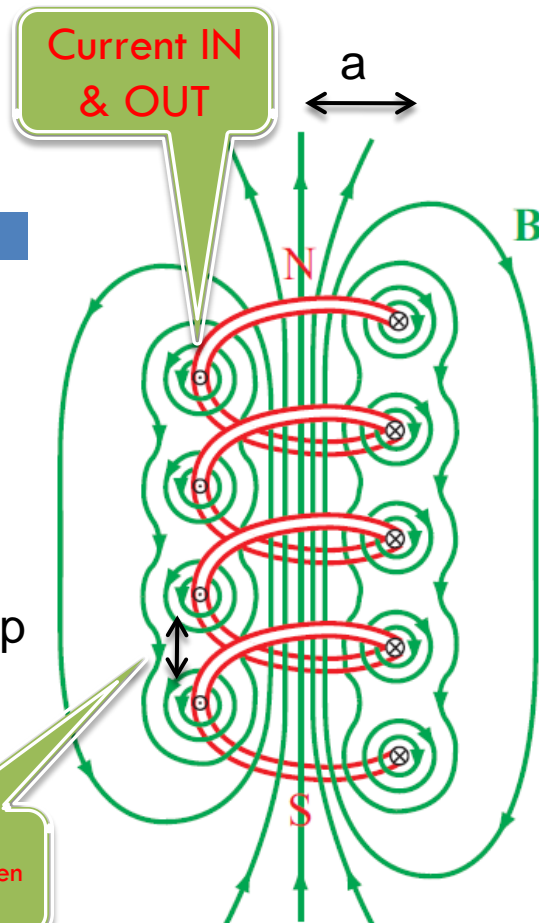
$n = \text{turns / meter} = N/l$

$N = \text{number of turns}$

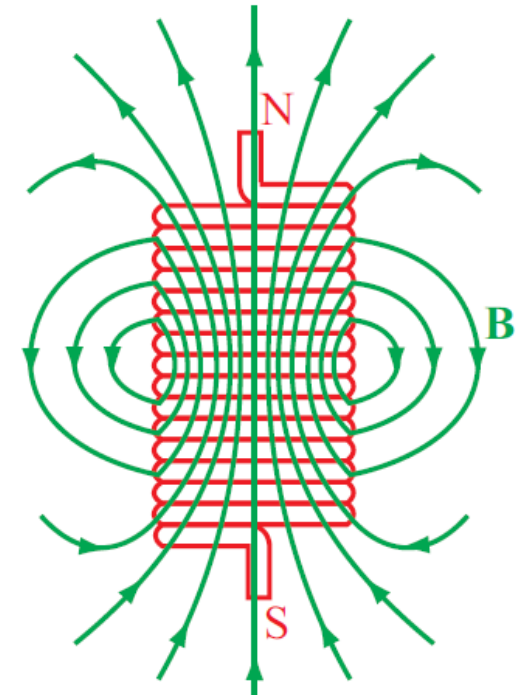
$I = \text{current along a single loop}$

$2a = \text{loop diameter}$

$dZ = \text{diff. distance between loops}$



(a) Loosely wound solenoid



(b) Tightly wound solenoid

For a single loop

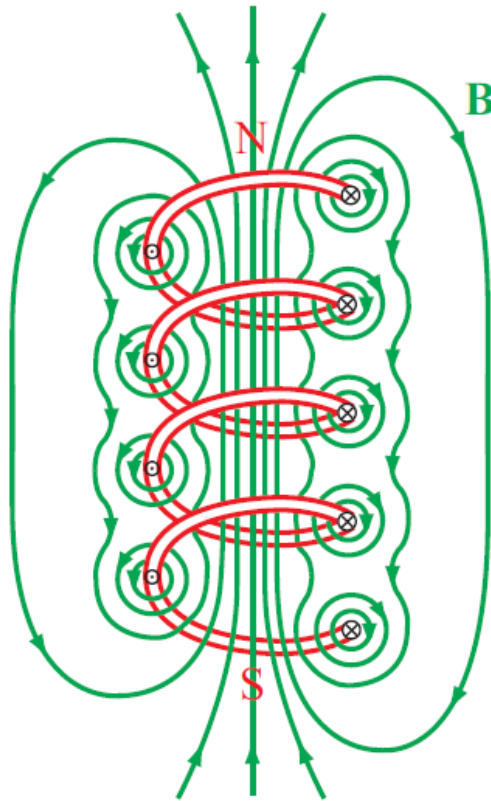
$$\mathbf{H} = \hat{\mathbf{z}} \frac{Ia^2}{2(a^2 + z^2)^{3/2}} \quad (\text{A/m})$$

For all N loops

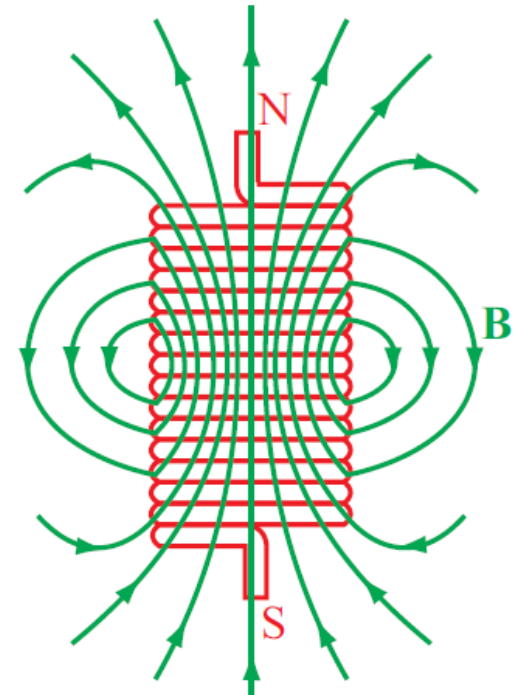
$$\mathbf{H} = \hat{\mathbf{z}} \frac{NIa^2}{2(a^2 + z^2)^{3/2}} \quad (\text{A/m})$$

$\longrightarrow dB = \mu dH ; N = n \cdot dz$

Solenoid



(a) Loosely wound solenoid



(b) Tightly wound solenoid

Inside the solenoid:

$$\mathbf{B} \simeq \hat{\mathbf{z}}\mu nI = \frac{\hat{\mathbf{z}}\mu NI}{l} \quad (\text{long solenoid with } l/a \gg 1)$$

Inductance

Magnetic Flux

$$\Phi = \int_S \mathbf{B} \cdot d\mathbf{s} \quad (\text{Wb}).$$

Flux Linkage

$$\Lambda = N\Phi = \mu \frac{N^2}{l} IS \quad (\text{Wb})$$

Inductance

$$L = \frac{\Lambda}{I} \quad (\text{H}).$$

Solenoid

$$L = \mu \frac{N^2}{l} S \quad (\text{solenoid}), \quad (5.95)$$

and for two-conductor configurations similar to those of Fig. 5-27,

$$L = \frac{\Lambda}{I} = \frac{\Phi}{I} = \frac{1}{I} \int_S \mathbf{B} \cdot d\mathbf{s}. \quad (5.96)$$